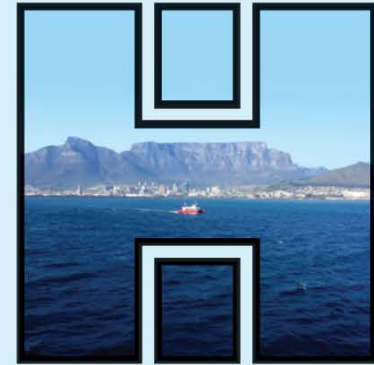




HYDRO2015

23-25 NOV. 2015 CAPE TOWN
DEVELOPING SUSTAINABLE HYDROGRAPHY IN AFRICA



Case study – the error budget of the positioning equipment for a sea mining vessel

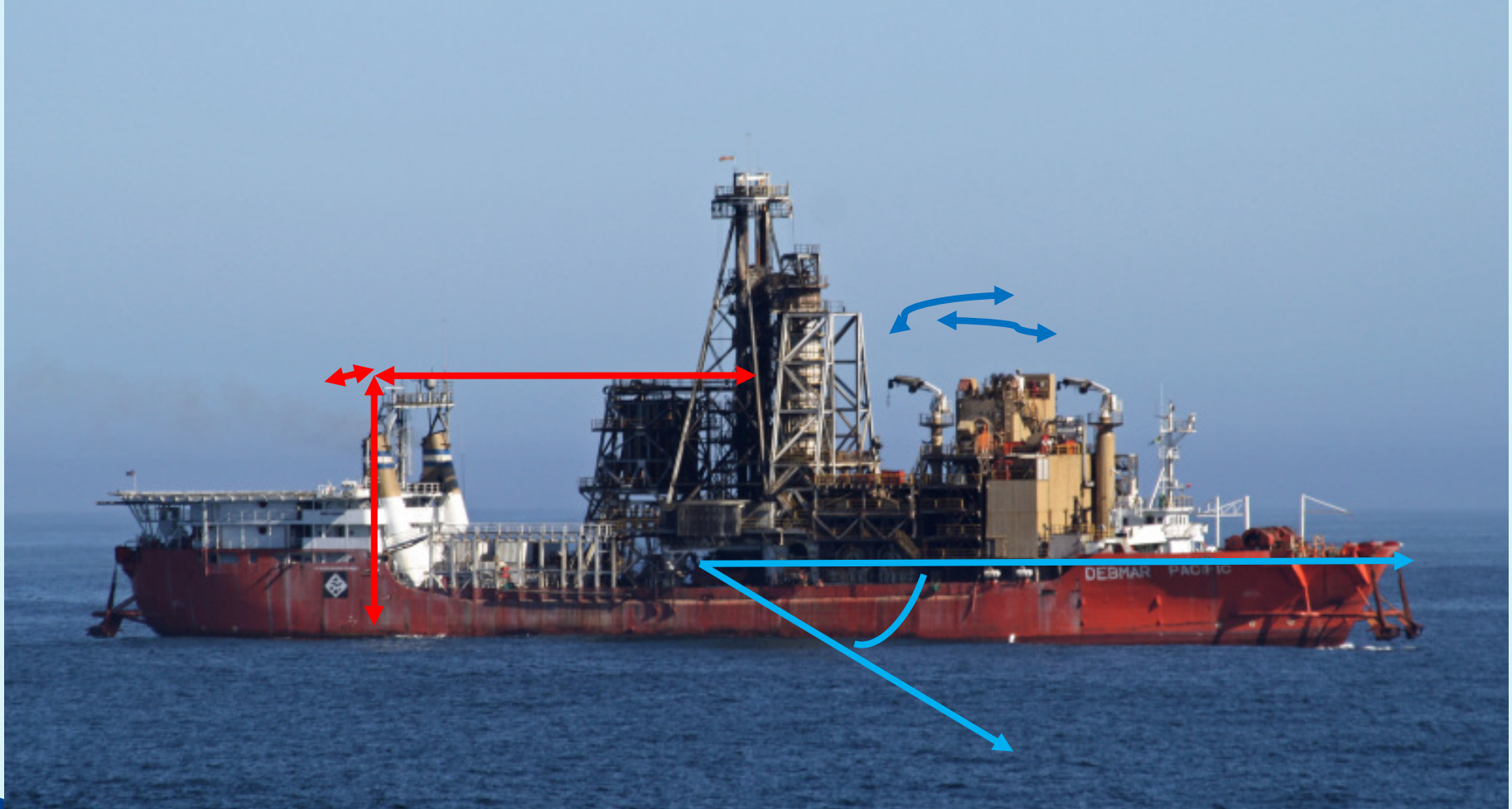
C. Jendrissek

Debmarine Namibia

Namibia



How precisely must all this be known?



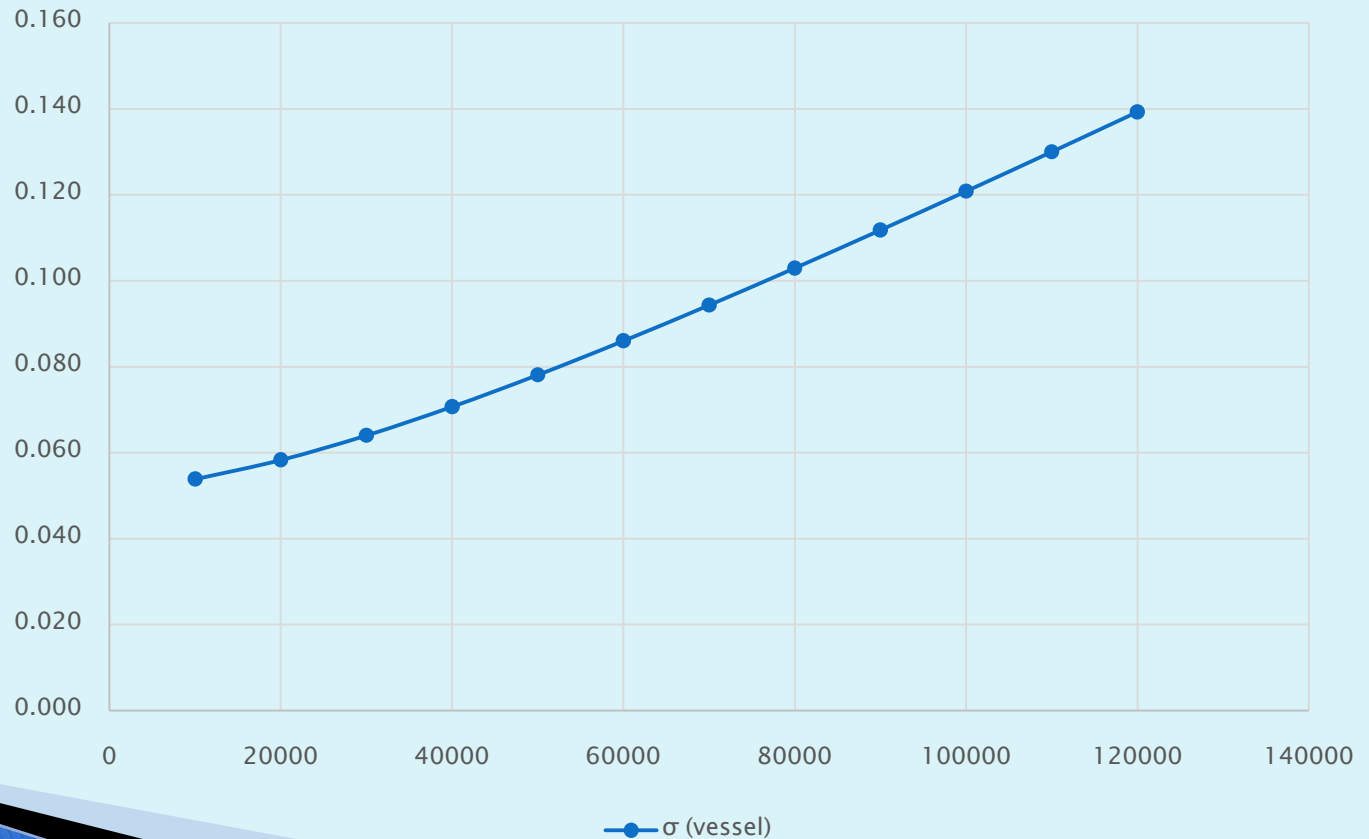
How precisely must all this be known?

- ❖ Breakdown into its separate components
 - ❖ GPS precision
 - ❖ Roll, pitch and gyro angles
 - ❖ Offset value precision

GPS precision

❖ RTK GPS vs satellite broadcast correction service

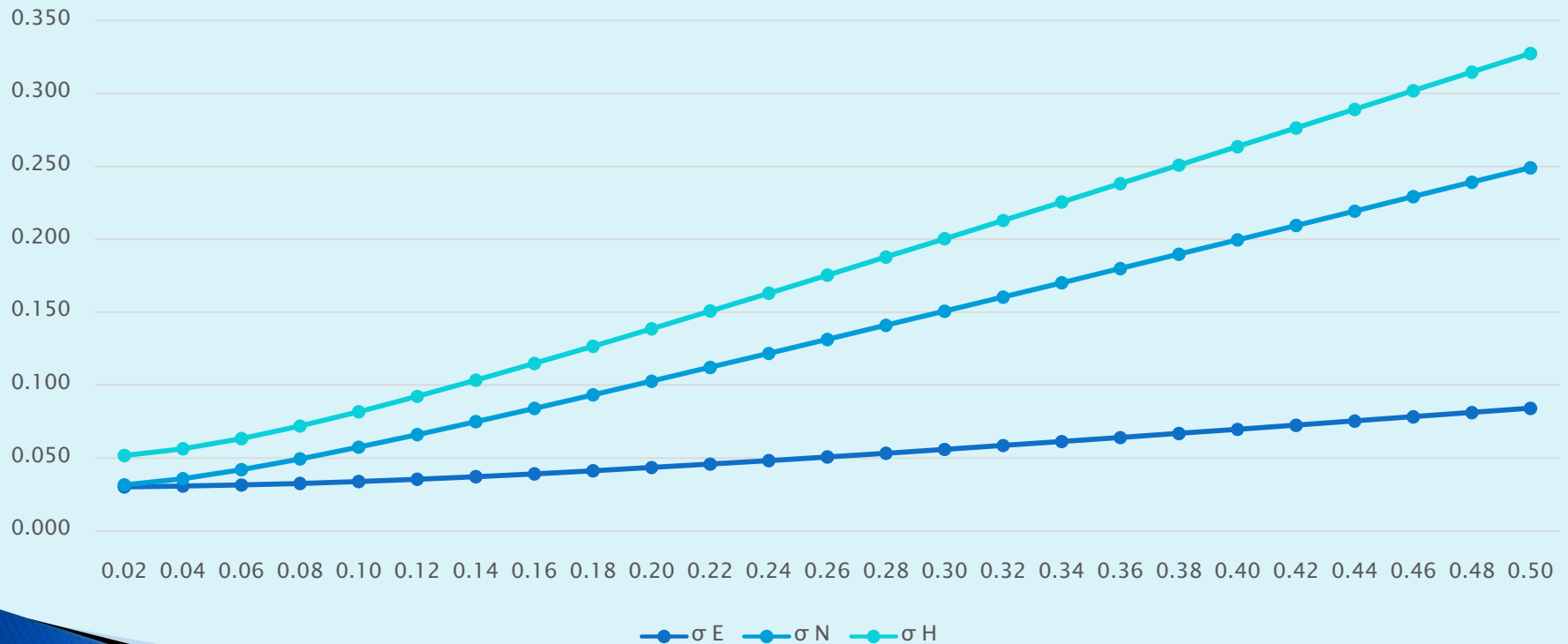
σ (RTK GPS on vessel)



Effect of roll, pitch and gyro error

- ❖ Effect of MRU precision
- ❖ Effect of heading precision

Effect of roll, pitch and heading for a set of XYZ offsets



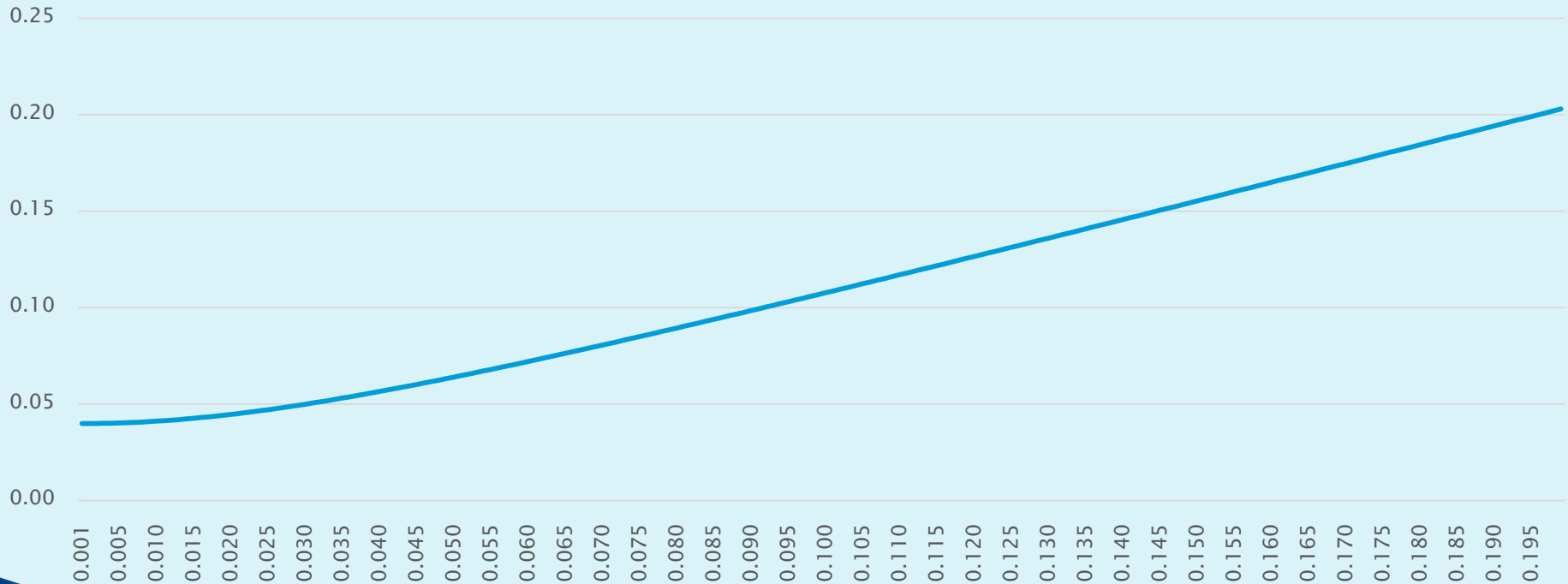
Attainable heading calibration

	ABC	
$\sigma^2(AB) = \sigma^2(CE) + \sigma^2(B) + \sigma^2(C)$	0.00019900	
$\sigma(AB)$	0.01411	°

How precise?

- ❖ How precisely must the heading value be determined so that the gyro's precision is not degraded?

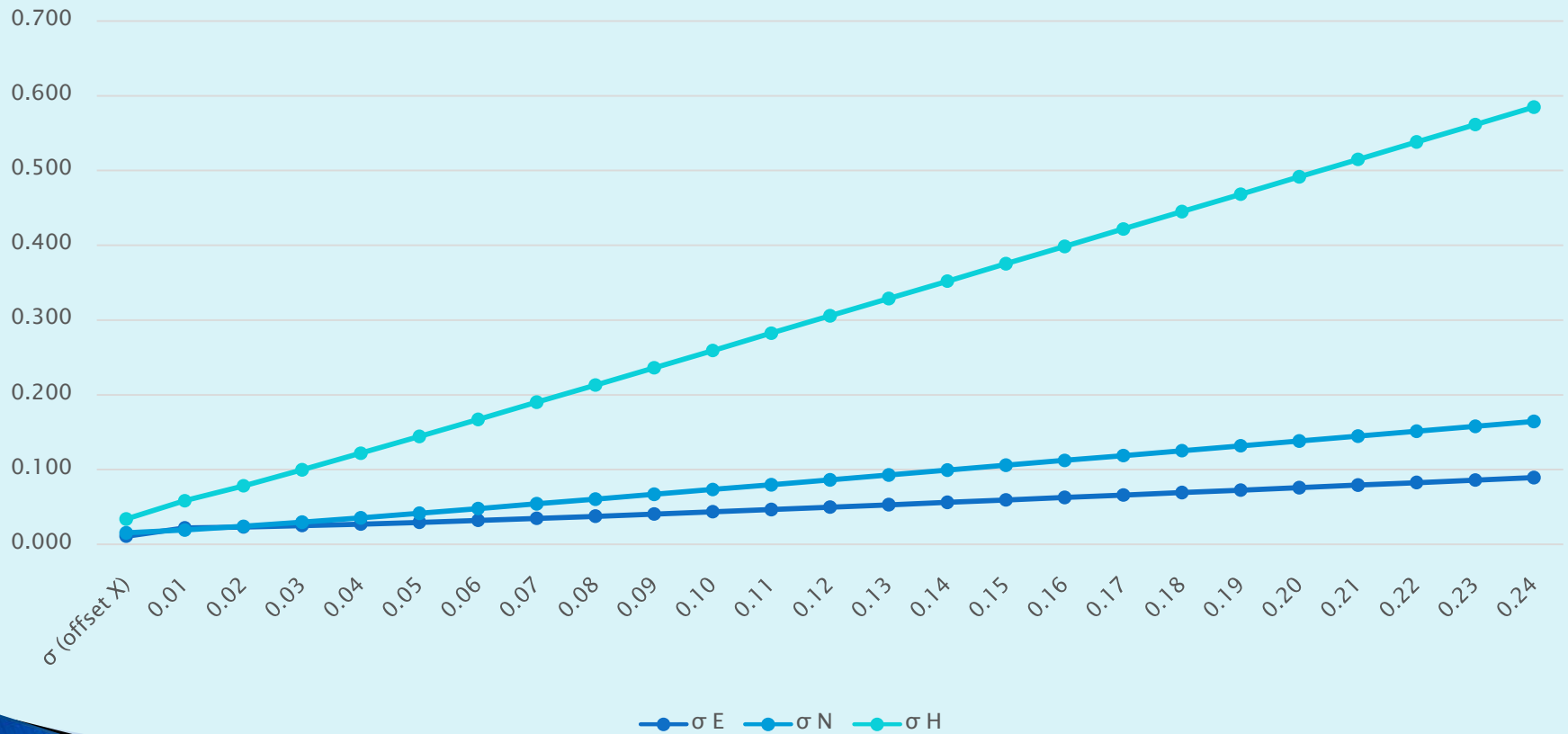
Total σ (degrees)



Precision of heading calibration

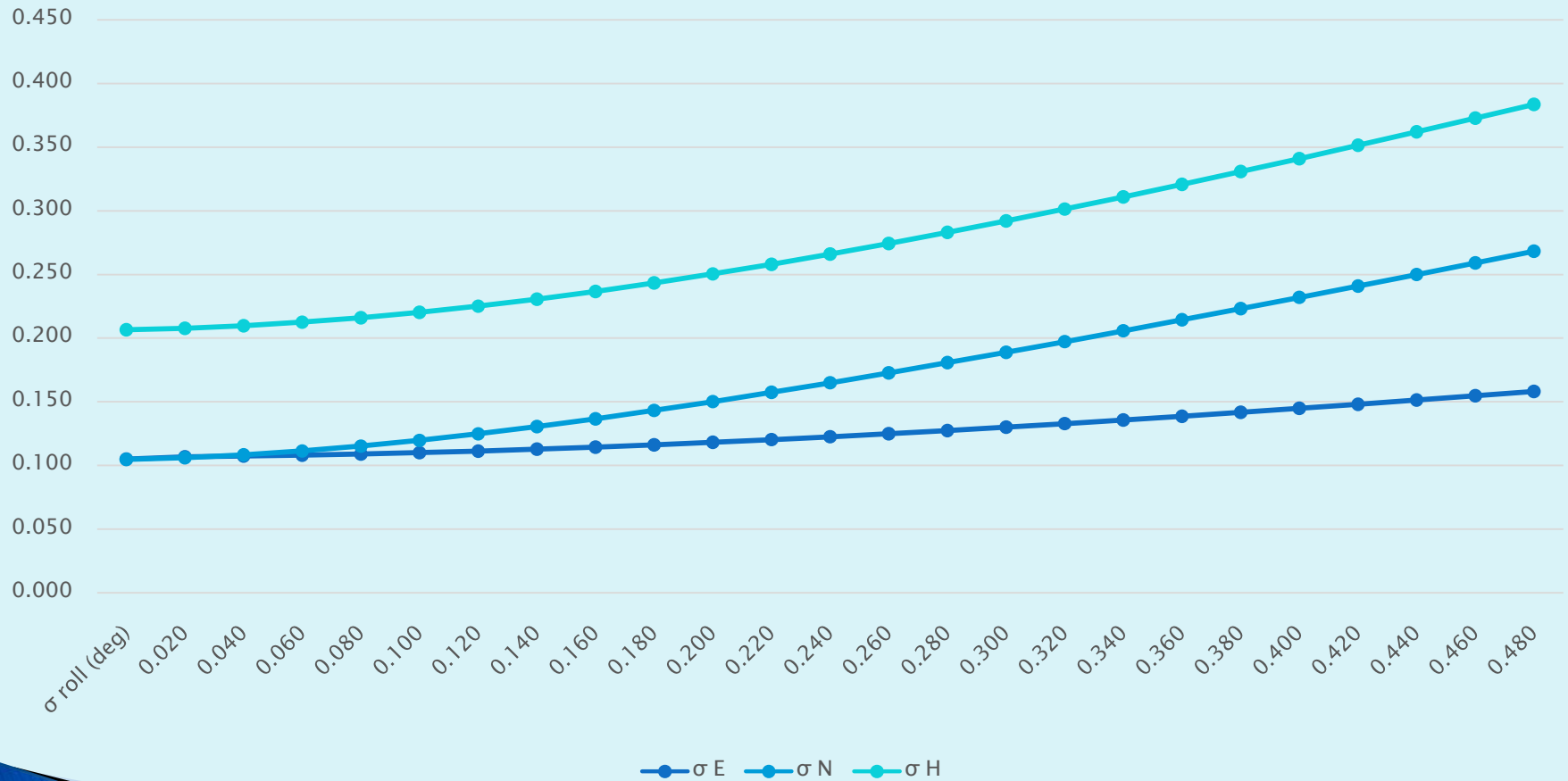
Effect of offset error

Effect of offset precision



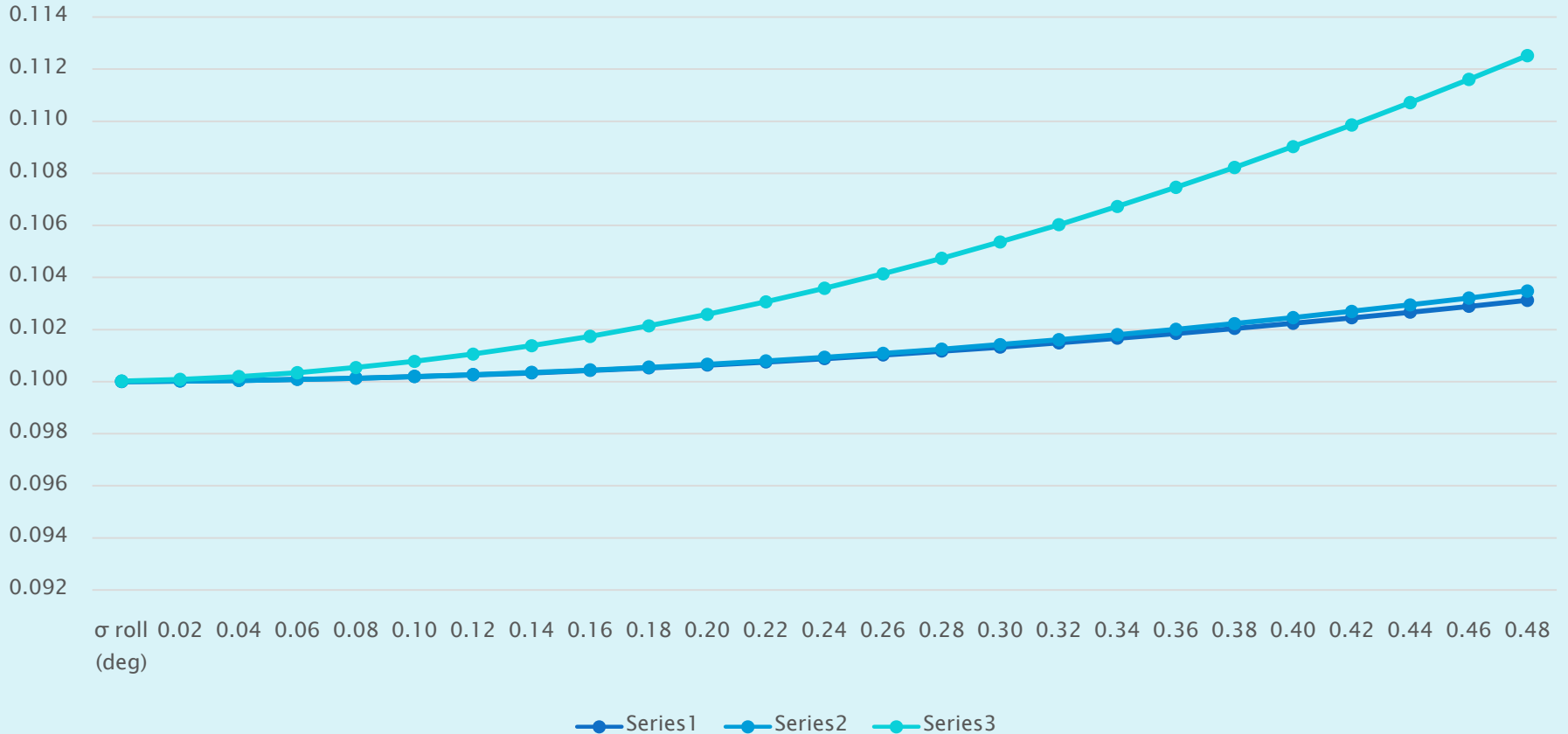
Combined effect

❖ Precision of the reference centre's position



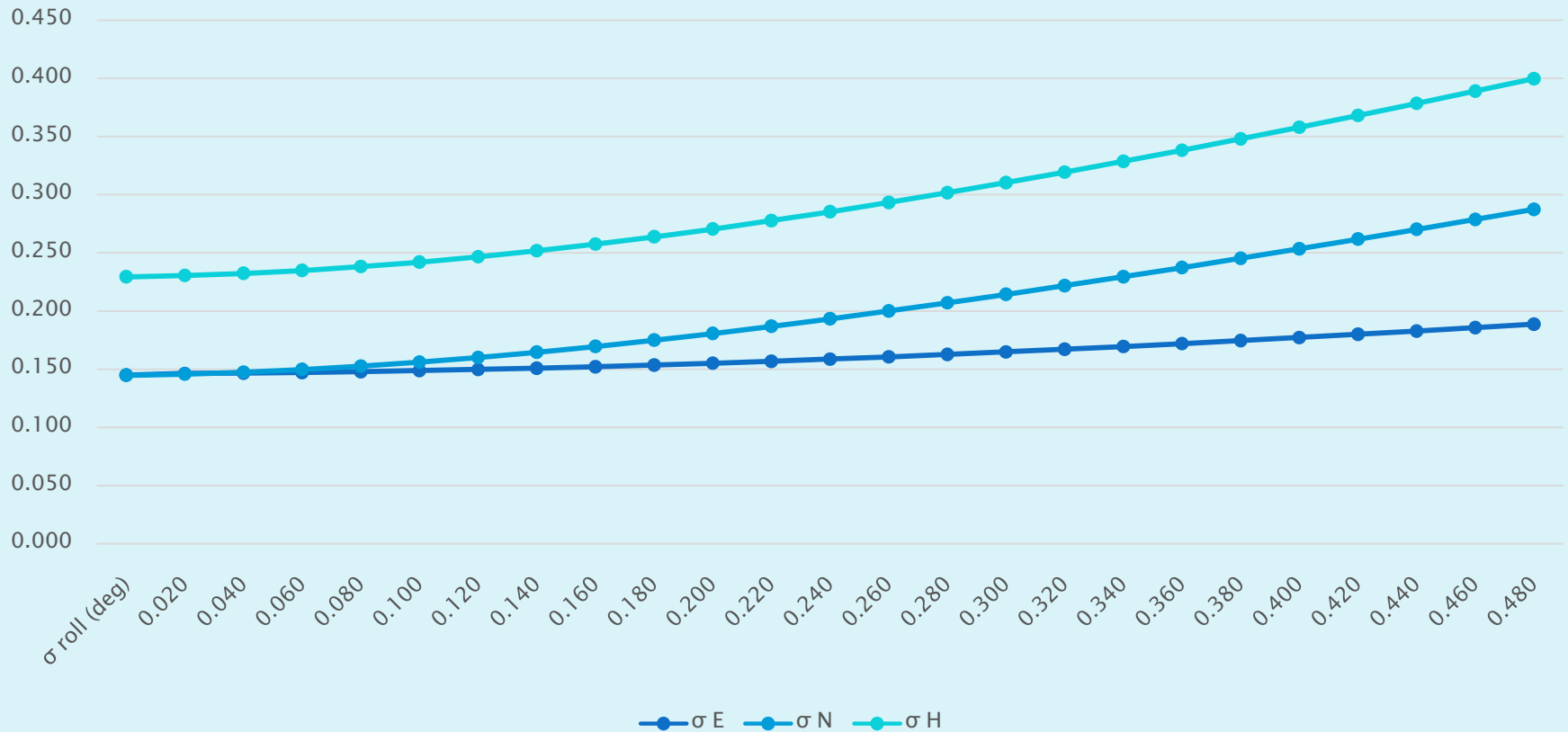
Acoustic precision

Effect of roll, pitch, heading on acoustic position for a set of offsets and ranges



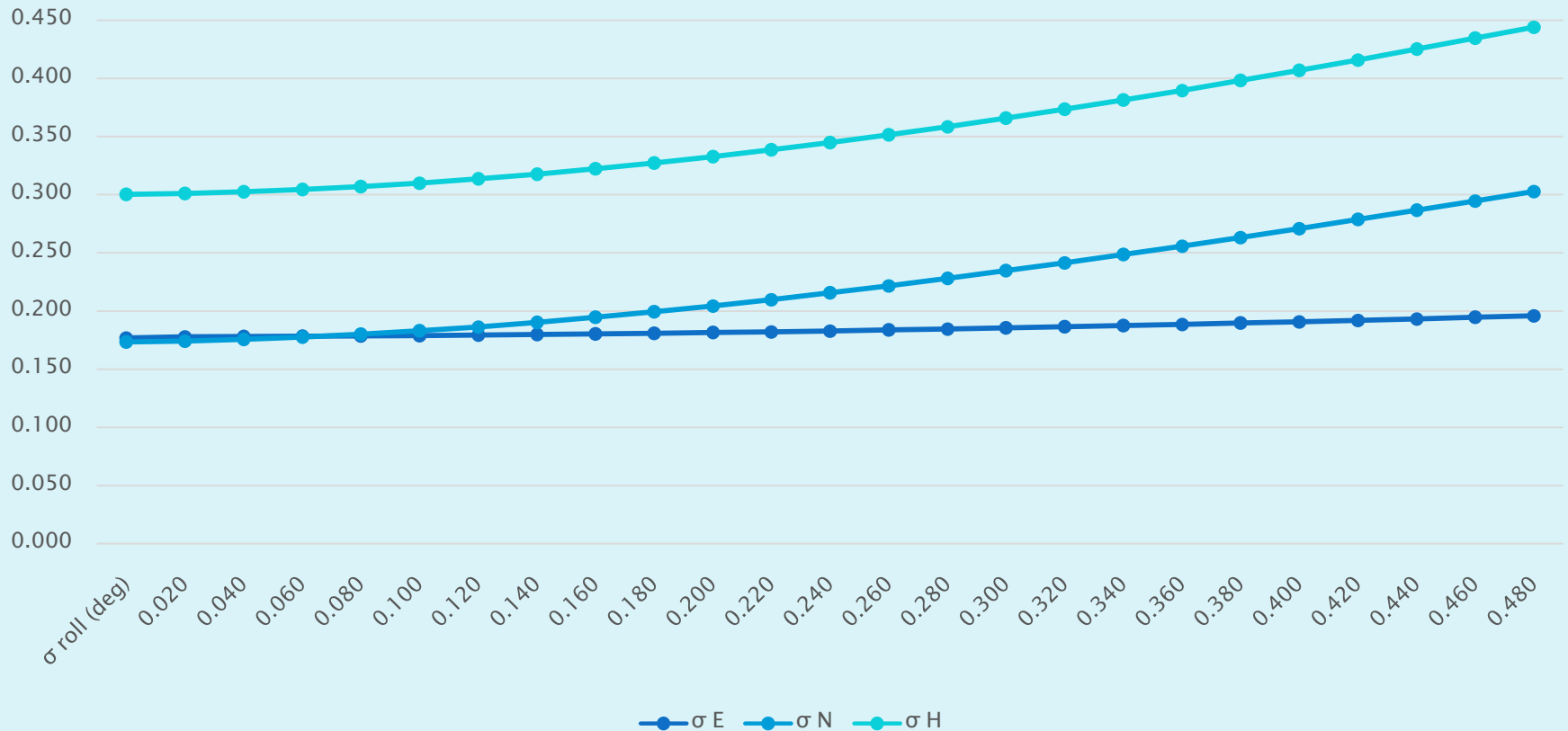
Overall combined effect

Precision of the final position: - 0.03; 0.03; 0.06 offset error



Effect of degraded offset precision

Precision of the final position: 0.10; 0.10; 0.20 offset error



Conclusion

- ❖ Position of geological sampling
- ❖ Sampling tool is much larger than the errors
- ❖ Requires geostatistical calculations to determine limit.



Thank you